

Neel P. Bhatt

ASSISTANT PROFESSOR · SCHOOL OF ENGINEERING AND COMPUTER SCIENCE · SYSTEMS ENGINEERING

The University of Texas at Dallas, Richardson, USA

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Research Interests

Verification-Centric AI, Neurosymbolic Learning, Multi-Modal Generative Models, Assured Perception and Planning for Robotics, Computer Vision, Uncertainty Quantification, State Estimation, Sequential Decision-Making, Autonomous Systems, Real-World Deployment.

Education

University of Waterloo

Sept 2018 - May 2023

Doctor of Philosophy (PhD) - Mechatronics Engineering (Advisors: [A Khajepour](#) and [E Hashemi](#))

Waterloo, ON - Canada

- Research focus: Spatially-aware [multi-agent object motion prediction](#) for autonomous driving using RL and potential fields
- Project Lead: [WATonoBus: First Canadian all weather autonomous shuttle in operation on public roads](#)
- Head Course TA for [ME780: Autonomous Driving](#)
- **Courses:** ML, RL, DL, Robotics, Autonomous Driving, Adaptive Control, Tools for Software Eng., Mechatronics System Integration

University of Toronto

Sept 2014 - June 2018

Bachelor of Applied Science (BASC) with High Honours - Mechanical Eng. - Robotics Minor - GPA: 3.97/4

Toronto, ON - Canada

- Among the **top 3** winners for the [capstone design project competition](#) across the department
- Ranked in the **top 5%** of all students in the department
- **Courses:** Robotics, Mechatronics Principles, Mechatronics Systems: Design and Integration, Control Systems

Experience

The University of Texas at Dallas

Aug 2026 - Present

Assistant Professor, [Systems Engineering](#)

Austin, TX - USA

- Leading research centered at developing trustworthy autonomous systems using multi-modal foundational models for sequential decision-making and assured active perception.

The University of Texas at Austin

Sept 2023 - Aug 2026

Research Scientist (Since Jul 2025); Postdoctoral Fellow (Prev.), [Center for Autonomy, Oden Institute](#)

Austin, TX - USA

- Working with Professor [Atlas Wang](#) and [Ufuk Topcu](#) as a part of the [Autonomous Systems Group](#) and the [VITA Research Group](#) at UT Austin.
- Research centered at developing neurosymbolic architectures for generative AI, trustworthy sequential decision-making using multi-modal foundational models, and assured active perception for autonomous systems.
- Leading verification-centric perception and planning architectures for rapid transfer and scaling as part of [DARPA ANSR](#) and [TIAMAT](#) programs.

University of Waterloo

Sept 2018 - Sept 2023

Lead Research Scientist, [WATonoBus Autonomous Shuttle](#)

Waterloo, ON - Canada

- Developed and implemented hardware and software architecture for perception, prediction, and decision-making including auto startup launch scripts, custom packages and drivers (Python/C++), multi-sensor fusion, system integration (ROS), and visualization.
- Led a team of several graduate students [achieving permit for daily operation and testing on public roads](#) as part of ministry's pilot program.

University of Alberta

Jan 2021 - Present

Visiting Research Scholar, [NODE Lab](#)

Edmonton, AB - Canada

- Worked with [Professor Ehsan Hashemi](#) on several [research projects](#) covering RL-based decision making for human-autonomous system hand-over, visual and inertial odometry, SLAM, object detection, cooperative perception, and supervised several graduate students.
- Developed and implemented hardware and software architecture for NODE Lab's autonomous vehicle.

General Motors R&D

May 2019 - Sept 2019

AV Software Engineering Intern, [GM Global R&D Tech Center](#)

Detroit, MI - USA

- Designed and implemented a novel real-time supervisory DL framework for vehicle velocity estimation consisting of a LSTM-based network architecture achieving > 95% accuracy on a large test set (Python, PyTorch) – ROI for patent submitted.
- Automated data generation and augmentation to ensure class balance and generalizability.

WATonomous Self-Driving Vehicle

May 2018 - Aug 2019

Perception Team Core Member, [GM AutoDrive Challenge](#)

Waterloo, ON - Canada

- Worked on the [WATonomous](#) self-driving vehicle, training TensorFlow based object detection models with data augmentation to classify traffic lights and achieved higher accuracy on test images specific to application.

Clearpath Robotics

May 2017 - Sept 2017

Applications Engineering Intern, **Research and Development Center**

Waterloo, ON - Canada

- Conducted [robot simulations](#) with Gazebo and ROS for line/person following demos presented at IROS 2017.
- Design focused on addressing needs of robot autonomy team for effective image processing, recognition, and control.

University of Toronto

May 2016 - Sept 2016

Research Intern, **Robotics Institute (NSERC USRA)**

Toronto, ON - Canada

- Worked with [Professor Yu Sun](#) at the [Robotics Institute](#), specifically at the Advanced Micro and Nanosystems Lab.
- Designed and fabricated an easy to use and maintain system for vibration and acoustic isolation of one of a kind Atomic Force Microscope (AFM) with resolution better than 0.05 nm.

University of Toronto

May 2015 - Sept 2015

Research Intern

Toronto, ON - Canada

- Worked with [Professor Chul B. Park](#) and analyzed discrete event procedures and algorithms, studied mathematical structures behind, and designed experiments toward parametric study and simulation of relevant parameters that govern the geometry of cellular plastic structures.

Publications

* Denotes equal contribution and co-first authorship

Journal Articles

- [J1] [Gaussian Process-Driven Monocular Vision-Based State Estimation for Autonomous Navigation](#)
Yunchen Ge, **Neel P. Bhatt**, Ehsan Hashemi
Robotics and Autonomous Systems, 2026
- [J2] [Design of a 3D High-Definition Map Visualizer for Pose Estimation and Autonomous Navigation in Dynamic Environments](#)
Yunchen Ge, Marcelo Contreras, Neel P. Bhatt, Ehsan Hashemi
Sensors, 2026
- [J3] [Neurosymbolic AI as an Antithesis to Scaling Laws](#)
Alvaro Velasquez, **Neel P. Bhatt**, Ufuk Topcu, Zhangyang Wang, Simon Stepputtis, Sandeep Neema, Gautam Vallabha
Proceedings of the National Academy of Sciences (PNAS) Nexus, 2025
- [J4] [Real-Time Privacy Preservation for Robot Visual Perception](#)
Minkyu Choi*, Yunhao Yang*, **Neel P. Bhatt***, Kushagra Gupta, Sahil Shah, Aditya Rai, David Fridovich-Keil, Ufuk Topcu, Sandeep Chinchali
Accepted at Transactions on Machine Learning Research (TMLR), 2025
- [J5] [Adaptive and Soft Constrained Vision-Map Vehicle Localization Using Gaussian Processes and Instance Segmentation](#)
Bruno Henrique Groenner Barbosa, **Neel P. Bhatt**, Amir Khajepour, Ehsan Hashemi
Expert Systems with Applications, 2025
- [J6] [DynaNav-SVO: Dynamic Stereo Visual Odometry With Semantic-Aware Perception for Autonomous Navigation](#)
Marcelo Cabrera, **Neel P. Bhatt**, Ehsan Hashemi
IEEE Transactions on Intelligent Vehicles (T-IV), 2024
- [J7] [A Survey on 3D Object Detection in Real-Time for Autonomous Driving](#)
Marcelo Cabrera, Aayush Jain, **Neel P. Bhatt**, Arunava Banerjee, Ehsan Hashemi
Frontiers in Robotics and Artificial Intelligence, 2024
- [J8] [Consensus-Based Information Filtering in Distributed LiDAR Sensor Network for Tracking Mobile Robots](#)
Isabella Luppi, **Neel P. Bhatt**, Ehsan Hashemi
Sensors, 2024
- [J9] [Object Reconstruction and Localization in Indoor Environments Using Infrastructure Sensor Node](#)
Soham Dasgupta, Venkata Devarakonda, Yifeng Cao, Minghao Ning, **Neel P. Bhatt**, Yufeng Yang, Ehsan Hashemi, Amir Khajepour
IEEE Sensors Journal, 2024
- [J10] [MPC-PF: Socially and Spatially Aware Object Trajectory Prediction for Autonomous Driving Systems Using Potential Fields \[SOTA\]](#)
Neel P. Bhatt, Amir Khajepour, Ehsan Hashemi
IEEE Transactions on Intelligent Transportation Systems (T-ITS), 2023
- [J11] [Integrated Inertial-LIDAR based Map Matching Localization for Varying Environments](#)
Xin Xia, **Neel P. Bhatt**, Amir Khajepour, Ehsan Hashemi
IEEE Transactions on Intelligent Vehicles (T-IV), 2023
- [J12] [Infrastructure-Aided Localization and State Estimation for Autonomous Mobile Robots](#)
Daniel Flögel, **Neel P. Bhatt**, Ehsan Hashemi
Robotics, 2022

Conference Papers

- [C1] [What Objects Enable, Not What They Are: Functional Latent Spaces for Affordance Reasoning](#)
Rohan Siva*, **Neel P. Bhatt***, Yunhao Yang, Seoyoung Lee, Nishant Gadde, Christian Ellis, Alvaro Velasquez, Zhangyang Wang, Ufuk Topcu
Accepted at Conference on Robot Learning (CoRL), 2026

- [C2] [VLN-Zero: Rapid Exploration and Cache-Enabled Neurosymbolic Vision-Language Planning for Zero-Shot Transfer in Robot Navigation \[Oral Spotlight\]](#)
Neel P. Bhatt, Yunhao Yang, Rohan Siva, Pranay Samineni, Daniel Milan, Zhangyang Wang, Ufuk Topcu
 Conference on Neuro-Symbolic Systems (NeuS), 2026
- [C3] [UNCAP: Uncertainty-Guided Planning Using Natural Language for CAVs](#)
Neel P. Bhatt*, Po-han Li*, Kushagra Gupta*, Rohan Siva, Daniel Milan, Alexander T. Hogue, Sandeep Chinchali, David Fridovich-Keil, Zhangyang Wang, Ufuk Topcu [\[Best Paper Award Finalist\]](#)
 International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2026, Paphos, Cyprus
- [C4] [Neurosymbolic LoRA: Why and When to Tune Weights vs. Rewrite Prompts \[1 of 3 papers selected for Oral\]](#)
 Kevin Wang*, **Neel P. Bhatt***, Junbo Li, Runjin Chen, Yihan Xi, Alvaro Velasquez, Ufuk Topcu, Zhangyang Wang
 Accepted at NeusymbBridge Workshop @ AAAI, 2026, Singapore
- [C5] [Comp4D: LLM-Guided Compositional 4D Scene Generation](#)
 Dejie Xu, Hanwen Liang, **Neel P. Bhatt**, Hezhen Hu, Hanxue Liang, Konstantinos N. Plataniotis, Zhangyang Wang
 Accepted at the Winter Conference on Applications of Computer Vision (WACV), 2026, Tucson, USA
- [C6] [Know Where You're Uncertain When Planning with Multimodal Foundation Models: A Formal Framework \[1 of 61 accepted papers\]](#)
Neel P. Bhatt*, Yunhao Yang*, Rohan Siva, Daniel Milan, Ufuk Topcu, Zhangyang Wang
 Conference on Machine Learning and Systems (MLSys), 2025, Santa Clara, USA
- [C7] [On The Planning Abilities of OpenAI's o1 Models: Feasibility, Optimality, and Generalizability \[65K YouTube Views\]](#)
 Kevin Wang*, Junbo Li*, **Neel P. Bhatt***, Yihan Xi, Qiang Liu, Ufuk Topcu, Zhangyang Wang
 Language Gamification Workshop @ NeurIPS, 2024, Vancouver, Canada
- [C8] [Fine-Tuning Language Models Using Formal Methods Feedback: A Use Case in Autonomous Systems \[1 of 37 accepted papers\]](#)
 Yunhao Yang*, **Neel P. Bhatt***, Tyler Ingebrand*, William Ward, Steven Carr, Zhangyang Wang, Ufuk Topcu
 Conference on Machine Learning and Systems (MLSys), 2024, Santa Clara, USA
- [C9] [MM3DGS SLAM: Multi-modal 3D Gaussian Splatting for SLAM Using Vision, Depth, and Inertial Measurements \[Oral Pitch Finalist\]](#)
 Lisong C. Sun*, **Neel P. Bhatt***, Jonathan C. Liu, Zhiwen Fan, Zhangyang Wang, Todd E. Humphreys, Ufuk Topcu
 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2024, Abu Dhabi, UAE
- [C10] [Fine-Tuning Language Models Using Formal Methods Feedback](#)
 Yunhao Yang*, **Neel P. Bhatt***, Tyler Ingebrand*, William Ward, Steven Carr, Zhangyang Wang, Ufuk Topcu
 Neuro-Symbolic Learning and Reasoning in the Era of Large Language Models (NucLeaR) Workshop @ AAAI, 2024, Vancouver, Canada
- [C11] [WATonoBus: Field-Tested All-Weather Autonomous Shuttle Technology](#)
Neel P. Bhatt, Ruihe Zhang, Minghao Ning, Alghooneh Ahmad, Chen Sun, Pouya Panahandeh, Ehsan Mohammadbagher, Ted Ecclestone, Ben MacCallum, Ehsan Hashemi, Amir Khajepour
 IEEE Intelligent Transportation Systems Conference (ITSC), 2024, Edmonton, Canada
- [C12] [LiDAR-Based Navigation Using Normal Distributions Transform Filter](#)
 Ali Shafieezadeh, **Neel P. Bhatt**, Ehsan Hashemi
 IEEE Intelligent Transportation Systems Conference (ITSC), 2024, Edmonton, Canada
- [C13] [A Stereo Visual Odometry Framework with Augmented Perception for Dynamic Urban Environments](#)
 Marcelo Cabrera, **Neel P. Bhatt**, Ehsan Hashemi
 IEEE Intelligent Transportation Systems Conference (ITSC), 2023, Bilbao, Spain
- [C14] [MPC-PF: Social Interaction Aware Trajectory Prediction of Dynamic Objects for Autonomous Driving Using Potential Fields](#)
Neel P. Bhatt, Amir Khajepour, Ehsan Hashemi
 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022, Kyoto, Japan
- [C15] [Augmented Visual Localization Using a Monocular Camera for Autonomous Mobile Robots](#)
 Ali Salimzadeh, **Neel P. Bhatt**, Ehsan Hashemi
 IEEE International Conference on Automation Science and Engineering (CASE), 2022, Mexico City, Mexico
- [C16] [Real-Time Pedestrian Localization and State Estimation Using Moving Horizon Estimation](#)
 Ehsan Mohammadbagher*, **Neel P. Bhatt***, Ehsan Hashemi, Baris Fidan, Amir Khajepour
 IEEE Intelligent Transportation Systems Conference (ITSC), 2020, Rhodes, Greece

Preprints

- [P1] [If, Then, Otherwise: Diagnosing Conditional Branching in Vision-Language Navigation](#)
 Seoyoung Lee, **Neel P. Bhatt**, Pranay Samineni, Cong Liu, S. P. Sharan, Timothy Barclay, Gregory M. Wagner, Daniel Milan, Sandeep Chinchali, Ufuk Topcu, Zhangyang Wang
 arXiv preprint, 2026
- [P2] [Co-GLANCE: Uncertainty-Aware Active Perception for Heterogeneous Robot Teaming](#)
 Michal P. Podolinsky*, **Neel P. Bhatt***, Pranay Samineni, Rohan Siva, Christian Ellis, Ufuk Topcu
 arXiv preprint, 2026
- [P3] [VASO: Formally Verifiable Self-Evolving Skills for Physical AI Agents](#)
 Yunhao Yang*, **Neel P. Bhatt***, Kevin Wang, Samuel Tetteh, Zhangyang Wang, Ufuk Topcu
 arXiv preprint, 2026
- [P4] [Physically Viable World Models: A Case for Query-Conditioned Embodied AI](#)
 Adam J. Thorpe, Stepan Tretiakov, Cheng-Hsi Hsiao, Su Ann Low, Xingjian Li, Hassan Iqbal, **Neel P. Bhatt**, Ufuk Topcu, Krishna Kumar
 arXiv preprint, 2026

- [P5] [RepV: Safety-Separable Latent Spaces for Scalable Neurosymbolic Plan Verification](#)
Yunhao Yang, **Neel P. Bhatt**, Runjin Chen, Zhangyang Wang, Ufuk Topcu
arXiv preprint, 2025
- [P6] [Joint Verification and Refinement of Language Model for Safety-Constrained Planning](#)
Yunhao Yang, **Neel P. Bhatt**, William Ward, Zichao Hu, Joydeep Biswas, Ufuk Topcu
arXiv preprint, 2025

Book Chapters

- [B1] [Neuro-symbolic AI: Foundations and Applications - Toward Verifiable and Scalable In-context Fine-tuning in Neurosymbolic AI](#)
Neel P. Bhatt
Wiley, 2025

Thesis

- [T1] [Socially and Spatially Aware Motion Prediction of Dynamic Objects for Autonomous Driving](#)
Neel P. Bhatt
University of Waterloo, 2023

Patents

[Monocular Camera System Performing Depth Estimation Surrounding a Vehicle](#)

US Patent Pub No.: US2024/0338837 A1, Filing Date: Oct 22, 2022

[Deep Learning Supervisory Framework for Vehicle State Estimation](#)

Patent Application Pending

Grants

Automaton-Based Knowledge Distillation from Generative Language Models for Planning and Learning

[Office of Naval Research \(ONR\)](#)

Amount awarded: \$1.5M (2023-2026), Role: Team Lead

Verification-Guided and Belief-Certified Agentic AI Control for Data Centers

[Amazon Research Awards \(ARA\) - Agentic AI](#)

Under submission, Role: PI

Principled Uncertainty Quantification and Mitigation for LLMs in Planning

[DARPA I2O Artificial Intelligence Quantified \(AIQ\)](#)

Role: Co-PI

Compositional and Scalable Learning for Multi-Agent Systems Under Uncertainty

[Lockheed Martin Advanced Technologies Lab \(ATL\)](#)

Amount awarded: \$0.5M (2024-2026), Role: Team Lead

Compositional Transfer in Neurosymbolic Reinforcement Learning

[DARPA I2O Transfer from Imprecise and Abstract Models to Autonomous Technologies \(TIAMAT\)](#)

Amount awarded: \$3.7M (2024-2027), Role: Team Lead

Neuro-Symbolic Perception, Action, and Reasoning (NeuroSPAR)

[DARPA I2O Assured Neuro-symbolic Learning and Reasoning \(ANSR\)](#)

Amount awarded: \$3.25M (2023-2025), Role: Team Lead

Infrastructure Sensors-based Automated Driving: Development and Demonstration

[Mitacs and S2e Technologies Co.](#)

Amount awarded: \$310k (2020-2022), Role: Team Lead

Visual-Inertial Monitoring System for Discoveries on Safe Human-Autonomy Interactions in Dynamic Environments

[NSERC Research Tools and Instruments grants program \(RTI\)](#)

Amount awarded: \$143k (2022-2023), Role: Team Lead

WATonoBus - All Weather Waterloo Autonomous Shuttle Bus: A Testbed for Automated Driving and V2X Connectivity

[NSERC Research Tools and Instruments grants program \(RTI\)](#)

Amount awarded: \$150k (2021-2022), Role: Team Lead

Infrastructure Sensors-based Automated Driving: Development and Demonstration

[Mitacs and S2e Technologies Co.](#)

Amount awarded: \$310k (2020-2022), Role: Team Lead

Invited Talks

In-context Refinement of LLMs and VLMs Using Verification and Uncertainty Feedback

Invited Talk at [MIT Lincoln Lab](#), 2025

Invited Talk at [FM4Control Workshop](#), 2025

Invited Talk at University of Colorado Boulder, 2025

Invited Talk at [CMU Robotics Institute - Neurosymbolic AI Seminar](#), 2025

Invited Talk at [USC Automatic Control Lab](#), 2025

Fine-tuning Language Models Using Formal Methods Feedback

Invited Talk at [Hewlett Packard AI Labs](#), 2024

Invited Talk at [DESTION Workshop](#), 2024

Industry Talk for [Lockheed Martin Artificial Intelligence Center - Assured Autonomy Systems](#), 2024

Invited Talk at [Autonomous Mobile Robotics Lab](#), 2023

MM3DGS SLAM: Multi-modal 3D Gaussian Splatting for SLAM Using Vision, Depth, and Inertial Measurements

Poster Presentation at [National AI Institute for Foundations of Machine Learning \(IFML\)](#), 2024

Industry Talk at [NXP Innovation Lab](#), 2024

Poster Presentation at [Machine Learning Lab Symposium](#), 2024

Poster Presentation at [6G@UT Fourm](#), 2024 and 2023

DARPA Assured Neuro Symbolic Learning and Reasoning (ANSR) PI Meetings

Research Talk at CMU, 2024

Research Talk at UC Berkeley, 2023

Reliable State Estimation and Distributed Controls in Intelligent Vehicular Networks

Tutorial [Presenter and Organizer](#) for IEEE Intelligent Vehicles (IV), 2023

WATonoBus - Algorithms and Software Structure for an All Weather Shuttle

Guest Lecture for ECE495 at University of Waterloo, 2023

Object Detection with ROS and OpenCV, Multi-Modal Data Acquisition, and Visualization

Guest Lecture for MECE788 at University of Alberta, 2023

An Overview of the WATonoBus - Canada's First Autonomous 5G Shuttle

[Guest Lecture](#) at University of Waterloo, 2022

Awards

Queen Elizabeth II Graduate Scholarship in Science and Technology (QEII-GSST)

[2022 - 2023 & 2019 - 2020](#)

Government of Ontario

Waterloo, ON - Canada

[QEII-GSST](#) is a merit-based scholarship program based on academic excellence, research ability and potential in program of study, and communication and leadership abilities targeted specifically towards students in a research-based graduate program in STEM disciplines.

Ontario Graduate Scholarship (OGS)

[2021 - 2022 & 2020 - 2021](#)

Government of Ontario

Waterloo, ON - Canada

[OGS](#) is a merit-based scholarship program for Ontario's best graduate students in all disciplines of academic study.

Engineering Excellence Doctoral Fellowship (EEDF)

[2020 - 2021](#)

University of Waterloo

Waterloo, ON - Canada

[EEDF](#) is awarded to student researchers who were admitted directly to the PhD program from a Bachelor's degree.

NSERC Industrial Experience Award

[May 2017 - Sept 2017](#)

National Sciences and Engineering Research Council (NSERC)

Waterloo, ON - Canada

[Received](#) for conducting R&D at Clearpath Robotics as part of an internship.

NSERC Undergraduate Research Award

[May 2016 - Sept 2016](#)

National Sciences and Engineering Research Council (NSERC)

Toronto, ON - Canada

[Received](#) for conducting research with Professor Yu Sun during undergraduate studies.

President's Scholar Award

[2014 - 2015](#)

University of Toronto

Toronto, ON - Canada

[Received](#) for being one of the top 150 highly qualified students applying to first year of direct-entry undergraduate studies.

Service

Reviewing	ICLR ('25-'26), CVPR ('24-'26), CoRL ('24-'26), ECCV ('24-'26), IROS ('22-'26), ICRA ('21-'26), T-ITS ('20-'24), ITSC ('20-'24), IV ('20-'24), AAAI ('23), MSSP ('23), ICORR ('22), SMCS ('22-'23)
Committee	Sponsorship Chair and Area Chair, CoRL (2026); Associate Editor, Awards, Registration, and Publicity Chair ITSC (2024)
Workshops	Spatial Intelligence and Structured Reasoning for Embodied Navigation (SISREN) (CoRL 2026); Learning and Formal Methods for Robotics (LAFR) (IROS 2026)
Fellowships	MITACS Accelerate (2021-2022)
Tutorials	Reliable State Estimation and Distributed Controls in Intelligent Vehicular Networks (ITSC 2023)
Teaching	Head course teaching assistant for ME780 - Special Topics in Mechatronics: Autonomous Driving
Mentoring	Mentored > 15 PhD, 7 Masters, and 14 undergraduate students. Led 4th year senior design team to awards and FRC team to Worlds

Skills

Machine Learning	Pytorch, Transformers , Hugging Face, TensorFlow, Keras, OpenCV , scikit-learn.
Programming	Python, C++, ROS , CUDA, Linux, Shell (Bash/Zsh), $\text{\LaTeX}$, Markdown, Firebase, Git.
Simulation and Design	OpenAI Gym, CARLA , AirSim, Unreal, Gazebo, Simulink, SolidWorks, MasterCAM.
Hardware Interfacing	LIDARs, Cameras, RADARs , GNSS, IMU, Embedded Computing (NVIDIA Jetsons), Time Sync., CAN Bus, Arduino.